

HL 030820

IB/2004/051009



Europäisches  
Patentamt

European  
Patent Office

Office européen  
des brevets

REC'D 09 JUL 2004

WIPO

PCT

Bescheinigung

Certificate

Attestation

Die angehefteten Unterlagen stimmen mit der ursprünglich eingereichten Fassung der auf dem nächsten Blatt bezeichneten europäischen Patentanmeldung überein.

The attached documents are exact copies of the European patent application described on the following page, as originally filed.

Les documents fixés à cette attestation sont conformes à la version initialement déposée de la demande de brevet européen spécifiée à la page suivante.

Patentanmeldung Nr. Patent application No. Demande de brevet n°

03077006.9 ✓

**PRIORITY  
DOCUMENT**

SUBMITTED OR TRANSMITTED IN  
COMPLIANCE WITH RULE 17.1(a) OR (b)

Der Präsident des Europäischen Patentamts;  
im Auftrag

For the President of the European Patent Office

Le Président de l'Office européen des brevets  
p.o.

R C van Dijk



Anmeldung Nr:  
Application no.: 03077006.9 ✓  
Demande no:

Anmeldetag:  
Date of filing: 30.06.03 ✓  
Date de dépôt:

Anmelder/Applicant(s)/Demandeur(s):

Koninklijke Philips Electronics N.V.  
Groenewoudseweg 1  
5621 BA Eindhoven  
PAYS-BAS

Bezeichnung der Erfindung/Title of the invention/Titre de l'invention:  
(Falls die Bezeichnung der Erfindung nicht angegeben ist, siehe Beschreibung.  
If no title is shown please refer to the description.  
Si aucun titre n'est indiqué se referer à la description.)

Disk drive with improved tray control

In Anspruch genommene Priorität(en) / Priority(ies) claimed /Priorité(s)  
revendiquée(s)

Staat/Tag/Aktenzeichen/State/Date/File no./Pays/Date/Numéro de dépôt:

Internationale Patentklassifikation/International Patent Classification/  
Classification internationale des brevets:

G11B17/00

Am Anmeldetag benannte Vertragstaaten/Contracting states designated at date of  
filing/Etats contractants désignées lors du dépôt:

AT BE BG CH CY CZ DE DK EE ES FI FR GB GR HU IE IT LU MC NL  
PT RO SE SI SK TR LI

Disk drive with improved tray control

The invention relates in general to a disk drive, and more specifically to an optical disk drive comprising a tray for receiving a disk, the tray being supported for movement between a first position of being housed within a casing of the disk drive and a second position of being protruded outwardly from the casing, an electric motor for moving the tray between the first and second positions, and regulation means for regulating an electric current through the motor for regulating the rotation of the motor.

The invention also relates to a method for moving a tray of a disk drive between a first and a second position under control of an electric motor.

As is commonly known, an optical storage disk comprises at least one track, either in the form of a continuous spiral or in the form of multiple concentric circles, of storage space where information may be stored in the form of a data pattern. An optical disk drive comprises i.a. a tray for loading the disk drive, rotating means for receiving and rotating the optical disk, and light generation means for generating an optical beam, typically a laser beam, for scanning the storage track with said laser beam. Since the technology of optical disks in general, and the way in which information can be stored in an optical disk, is commonly known, it is not necessary to describe this technology in great detail.

In optical data storage devices, the medium (e.g. the CD, DVD, or BD disk) is loaded into the disk drive by a loader mechanism, which generally comprises the tray, a tilting mechanism, and a (magnetic) clamp. To play, c.q. read a disk, the user places the disk on the tray which, after the user presses a button or the tray itself, transports the disk into the disk drive. When the tray is inside the disk drive, the tilting mechanism tilts the turntable upwards such that the disk is lifted off the tray. The clamp, finally, fixes the disk onto the turntable. To eject the disk from the disk drive, the loader mechanism is driven in the reverse direction.

The loader mechanism (tray and tilting mechanism) is usually driven by a DC motor via a gear transmission. The electrical current  $I_m$  through the motor obeys the following equation:

$$V_m - V_{emf} = RI_m + L \frac{dI_m}{dt}. \quad (1)$$

$V_m$  is the voltage driving the motor,  $V_{emf}$  is the back-EMF voltage,  $R$  is the motor resistance, and  $L$  is the motor inductance. Usually a hardware switch (usually mechanical or optical) is included in the disk drive in order to detect whether the tray, c.q. the loader mechanism has completed an opening/closing action. Such a hardware switch is generally called a tray switch. It is known that the end stops of the tray motion can be detected by measurement of the tray motor current, as follows. When the tray hits one of the end stops, the motor blocks and consequently the back-EMF voltage generated by the motor drops. This causes a sudden and remaining increase of the motor current. This increase in motor current at the end stop can be detected by means of a level detection algorithm: if the current exceeds a certain limit for a certain amount of time, it is decided that the tray has reached a stop, and the motor is turned off. The motor current can e.g. be measured by placing a measuring resistor in series with the motor, and measuring the voltage across the resistor. Detection of the end stops from the motor current measurement obviates the need of a hardware (mechanical or optical) switch to detect the end stops. Detection of end stops by measuring current, and without a tray switch, will be called "switchless detection" in the following.

A shortcoming of the method of switchless detection, compared to the traditional tray switch method, is the uncertainty of the tray position. A tray switch gives complete certainty about whether the tray is actually closed: if the switch is closed, the tray must be at either one of its end positions. Switchless detection does not give full certainty about the actual position of the tray after a stop: it could be that the user of the disk drive has manually forced a tray stop at an intermediate position.

Another shortcoming of the method of switchless detection, compared to the traditional tray switch method, is the twisting motion of the tray as it hits the outside stop.

When using switchless detection, a stop is detected *after* the tray has been mechanically blocked by the end stop. For a short duration, the tray is simultaneously being driven by the motor, and blocked by the end stop. The force that the motor exerts on the tray generally does not attach to the center of gravity of the tray. Furthermore there generally is some mechanical play in the tray mechanism, particularly when the tray is at the outside position. Consequently, in this short phase in which the tray is driven and blocked at the same time, it can occur that the tray displaces sideways or twists. This kind of motions is undesired, especially in audio/video disk drives.

It is therefore an object of the invention to provide an improved method for detecting an end stop of a tray action.

- To achieve the object of the invention the disk drive as defined in the opening paragraph is characterized in that the regulation means comprises detection means for 5 detecting a back-electromotive signal (e.g. a voltage) produced during rotation of the motor for deriving position information of the tray with respect to the first and second positions.

In this way the position of the tray can be inferred from the electrical current through the motor without any additional hardware components.

- An embodiment of the disk drive is characterized in that the regulation means 10 regulates the electric current through the motor in a manner that during movement of the tray in the direction from one of the first and second position to the other one of the first and second position, the rotation of the motor gradually reduces when the position of the tray has reached in the neighborhood of one of the first and second position.

- By doing so, the earlier mentioned undesired sideways or twisted motion of 15 the tray is abolished or diminished.

The invention also includes the methods as defined in claims 3 and 4.

- The invention will be described in more detail with reference to the 20 accompanying drawings, in which:

Figure 1 shows a schematic drawing of a disk drive thereby illustrating the tray function;

Figure 2 shows a first flow chart demonstrating an inventive method for tray control of the disk drive; and

- 25 Figure 3 shows a second flow chart demonstrating the inventive method for tray control of the disk drive in respect of further improved stop control of the tray.

In these figures parts or elements having like functions or purposes bear the same reference symbols.

30

Figure 1 shows a schematic drawing of a disk drive DRV. The disk drive DRV is implemented in an outer casing CS. A tray TR for receiving and transporting a disk is made slideable into and out of the casing CS in a direction indicated by "x". The indicated position of the tray TR deviates slightly from the direction x. This is the situation which often

occurs in the known optical disk drives. It is caused by the fact that when the tray TR moves from a first position in which it is within the casing CS to a second position of being protruded outwardly from the casing CS, the movement of the tray TR has suddenly stopped by the blocking means (or end stop) BLK. As a consequence forces DRF cause a rotation RT

5 since generally the forces DRF do not attach to the center of gravity of the tray TR.

Furthermore there is generally some mechanical play in the tray mechanism. The tray TR is controlled by a motor (not indicated in figure 1). In the invention the stopping of the tray TR is initiated by information received from the back-EMF electromotive signal (voltage or current) of the motor. Also, preferably, with the aid of this information a slowdown or  
10 braking action can already be initiated at a short distance before the desired stopping position is reached.

The electromotive back-EMF voltage  $V_{emf}$  is proportional to the (angular) speed of the motor. It is expressed by the following equation:

$$15 \quad V_{emf} = K_e \frac{d\phi}{dt}. \quad (2)$$

$K_e$  is the so called back EMF constant of the motor.

Combining equation [2] and equation [1] results, after integration, in the following  
20 expression for the angular position of the motor at time  $t$ .

$$\phi(t) = \phi(0) + \frac{1}{K_e} \left( \int_0^t (V_m(t) - R I_m(t)) dt - L(I_m(t) - I_m(0)) \right). \quad (3)$$

Given that  $R$  and  $L$  are known, and assuming that  $\phi(0)=0$ , the above expression allows to  
25 infer the angular position of the motor, because  $V_m$  is known and  $I_m$  is measured by detection means. The detection means, which is part of the regulation means which regulates the motor (also in the known disk drives), can for instance be implemented by a resistor in series with the motor. The voltage across this resistor is then a measure for  $I_m$ . With respect to the position of the tray, denoted  $x$ , it holds that:

30

$$x = \alpha \phi, \quad (4)$$

with  $\alpha$  being some known constant. The position measurement can be simplified further by assuming that the motor inductance  $L$  is negligible, which is allowed in most cases. Then one only needs to know the value of the motor resistance  $R$ , in order to infer the position of the tray.

Figure 2 shows a first flow chart demonstrating an inventive method for tray control of the disk drive DRV. It illustrates how position measurement can be used to enhance switchless detection. If for example during a closing motion the tray TR is blocked (e.g. manually) at some intermediate position, the optical disk drive, using the inventive method, will subsequently respond by opening the tray TR and returning to its original (open) position. Position, c.q. displacement, information of the tray TR can be used to enhance switchless detection, as follows. Position information can be used by the tray open and close algorithm to conclude whether the tray TR has completed a full open or close motion. Proper action can be taken if the tray TR has only opened halfway, e.g. because a user has manually blocked the tray TR. The tray TR can be stopped just before it reaches the outside stop. This prevents twisting of the tray at the outside end stop. In this way, the shortcomings of switchless detection compared to detection with a tray switch are overcome.

Figure 3 shows a second flow chart demonstrating the inventive method for tray control of the disk drive in respect of further improved stop control of the tray TR. By the availability of the knowledge of the tray position during a tray movement the tray TR can be stopped in a very controlled and smooth manner. A slowdown or braking action can already be initiated at a short distance before the desired stopping position is reached. Even if a tray switch is present, measuring the position of the tray TR as described above can be beneficial. Using the tray switch, the exact position of the tray TR is only known when the tray TR is at either one of the end stops. Using position measurement, the tray position also is known when it is at intermediate positions. This information can be used to enhance the open/close algorithm, e.g. in the form of initiating a slowdown or braking action just before reaching the end stop.

Position measurement according to equation [3] requires computation of the integral  $\int_0^t (\gamma_m - RI_m)$ . In the actual digital implementation this integration can be approximated by a summation. In this case the position at sampling instant  $n$  is approximately given by

$$\phi[n] = \phi[0] + \frac{T}{K_e} \sum_{k=0}^n (V_m[k] - RI_m[k]). \quad (5)$$

Here,  $T$  represents the sampling time of the digital implementation. Note that equation [5] is the simplest possible approximation of the integral in equation [3]. Better approximations, such as trapezoidal approximation, Simpson's rule, and more elaborate methods can also be used. Such methods can be found in various well recognized handbooks.

5 The computation of tray position with equation [3] might be disturbed by measurement inaccuracies, noise, and drifts. Therefore, preferably, the measured position is calibrated once in a while. For this purpose it is advised to reset the measured position to zero (see figure 2) at each time that the tray TR is known to be inside the casing CS. If a disk is in the disk drive

10 DRV and it can be played, c.q. read by the disk drive DRV, then one is absolutely sure that the tray TR is at the inside position and the tray position can be reset to zero at this point.

CLAIMS:

1. A disk drive comprising a tray (TR) for receiving a disk, the tray (TR) being supported for movement between a first position of being housed within a casing (CS) of the disk drive and a second position of being protruded outwardly from the casing (CS), an electric motor for moving the tray (TR) between the first and second positions, and regulation means for regulating an electric current through the motor for regulating the rotation of the motor, characterized in that the regulation means comprises detection means for detecting a back-electromotive signal produced during rotation of the motor for deriving position information of the tray (TR) with respect to the first and second positions.
- 5 10 2. A disk drive according to claim 1, characterized in that the regulation means regulates the electric current through the motor in a manner that during movement of the tray (TR) in the direction from one of the first and second position to the other one of the first and second position, the rotation of the motor gradually reduces when the position of the tray (TR) has reached in the neighborhood of one of the first and second position.
- 15 3. A method for moving a tray of a disk drive between a first and a second position under control of an electric motor, characterized in that detection means detects a back-electromotive signal produced during rotation of the motor for deriving position information of the tray with respect to the first and second positions.
- 20 4. A method according to claim 3, characterized in that when the tray moves in the direction from one of the first and second position to the other one of the first and second position, and when the position of the tray comes nearby one of the first and second position, the rotation of the motor gradually reduces.

**ABSTRACT:**

A disk drive comprising a tray (TR) for receiving a disk, the tray (TR) being supported for movement between a first position of being housed within a casing (CS) of the disk drive and a second position of being protruded outwardly from the casing (CS), an electric motor for moving the tray (TR) between the first and second positions, and regulation means for regulating an electric current through the motor for regulating the rotation of the motor.

The regulation means comprises detection means for detecting a back-electromotive voltage produced during rotation of the motor for deriving position information of the tray (TR) with respect to the first and second positions.

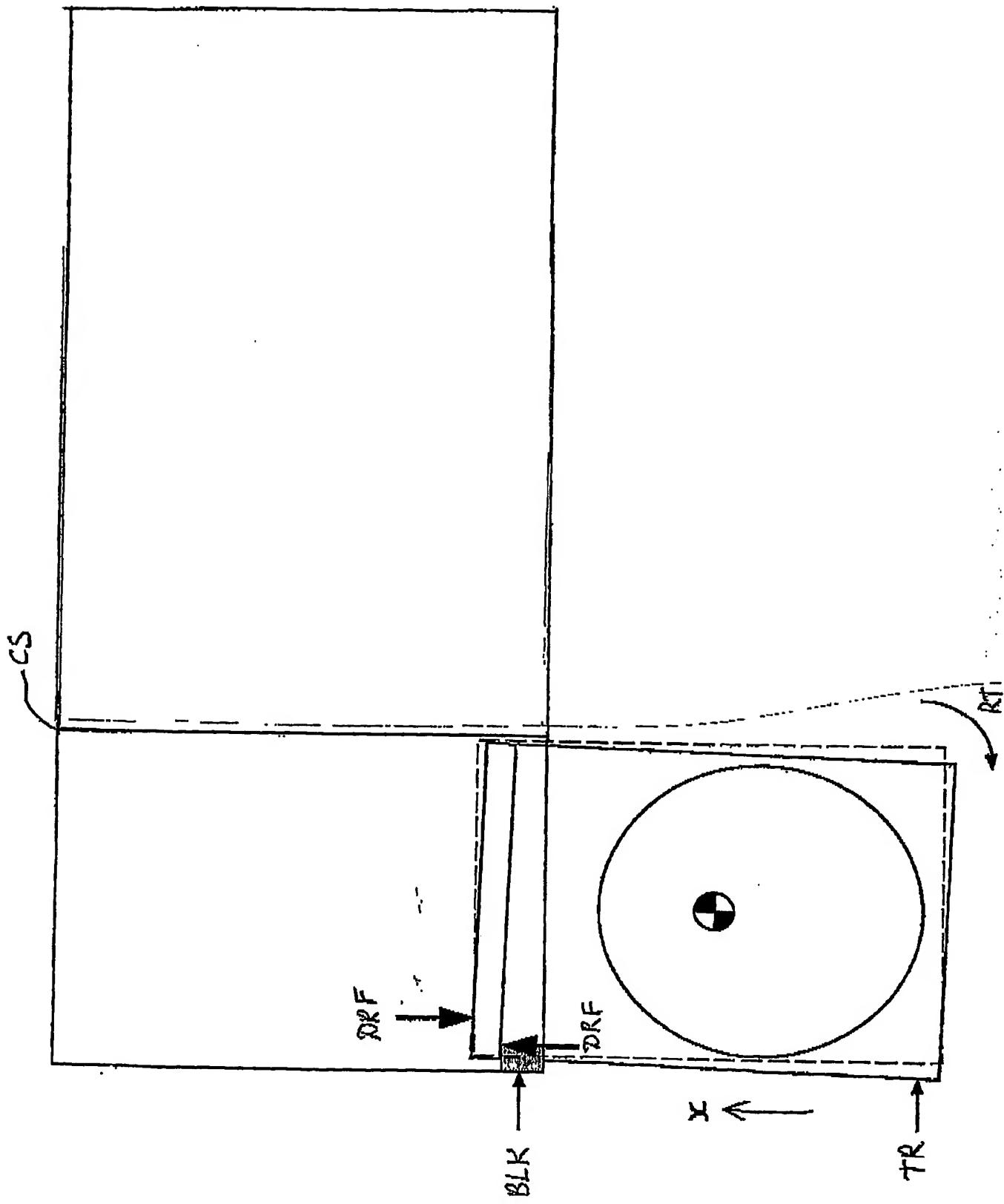
10

Fig. 1

30.JUN.2003 9:49

PHILIPS CIP NL +31 40 2743489

No.590 P.15/17  
015 30.06.2003 10:47:2



DRV

Fig.1

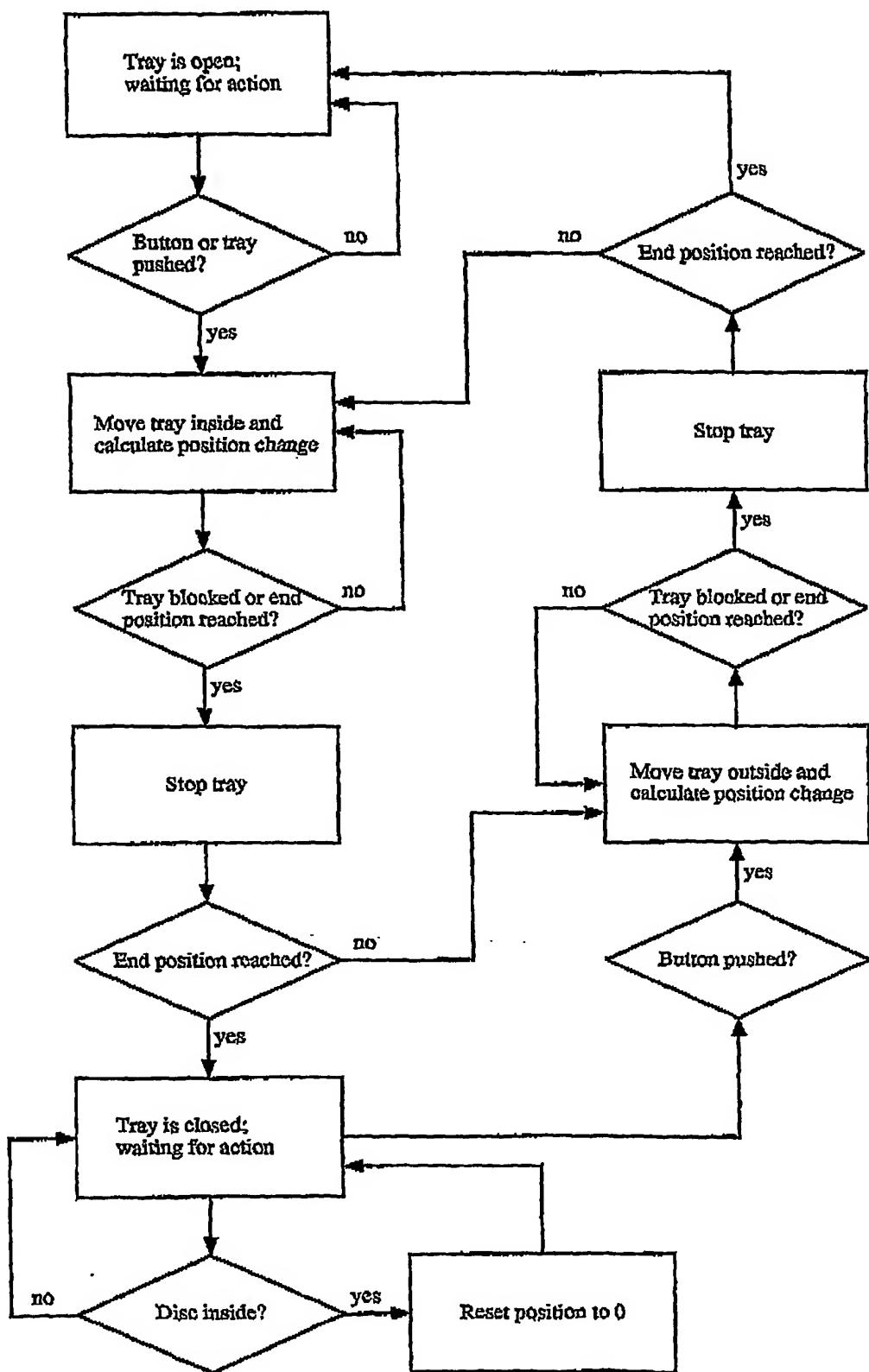
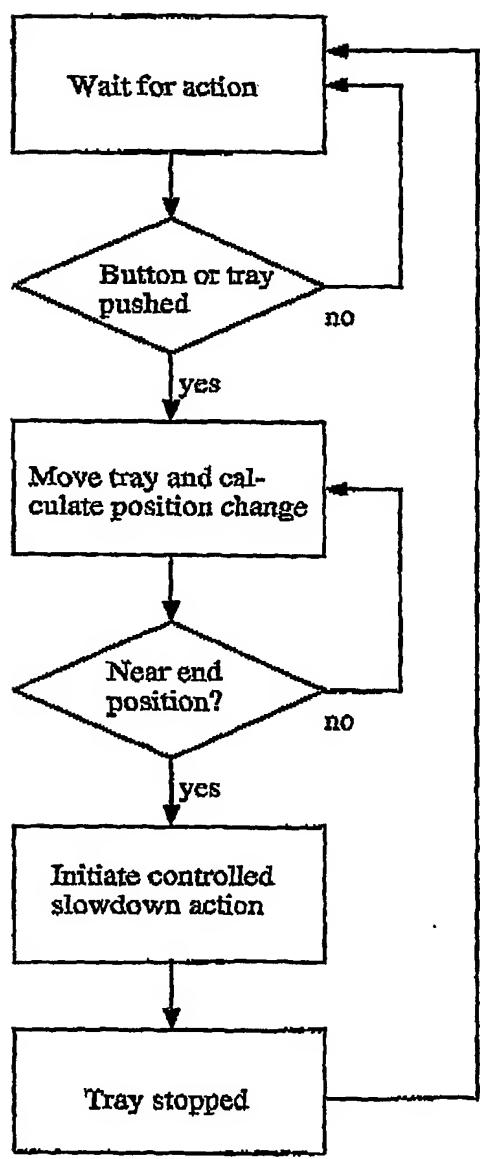


Fig. 2



Eig. 3

PCT/IB2004/051009

